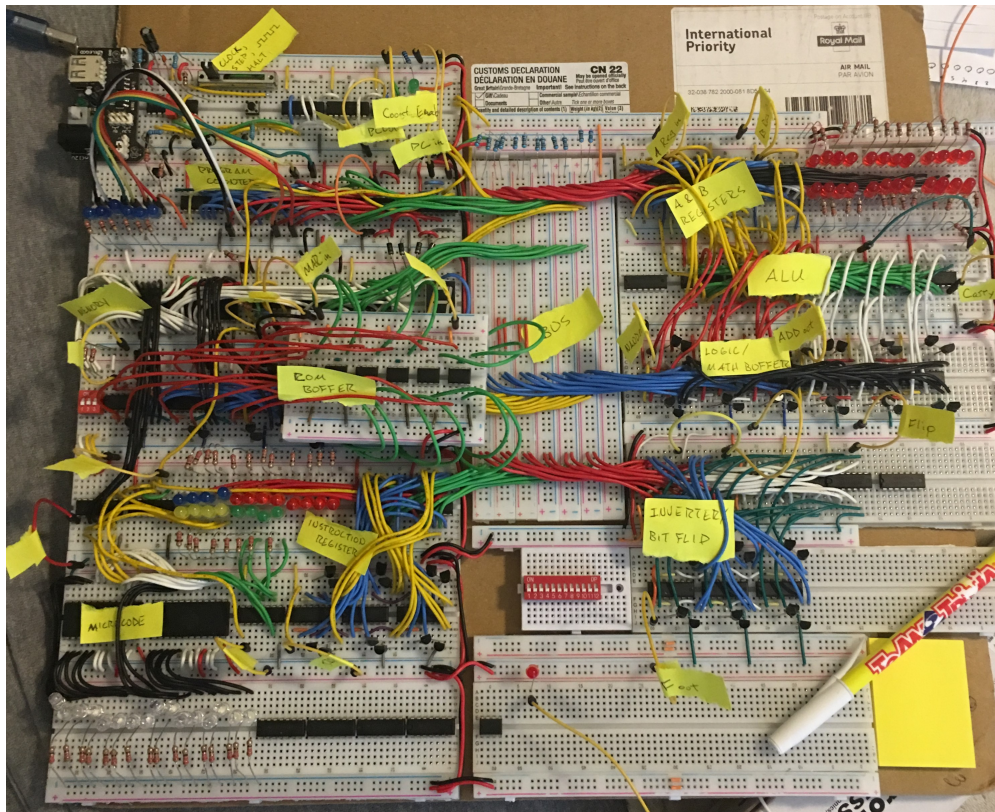


K.E.N.N.Y. v5.0 — User Guide

"Because sometimes you gotta die to get better..."

G. Riggs — 2020



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1 Who is K.E.N.N.Y.?

The “Kerneled Enumerable Natural Number Yammer” is a 12-bit breadboard computer design. In the absence of true RAM, memory is facilitated by 2x2KB EEPROMs, mapped in parallel to 64 program lines of 16-bit instructions, and 192 addresses (12 bits each); this leaves 3 bits free, partitioning the memory into 8 program blocks. The instructions are encoded, where 16 bits manipulate 21 control signals with the assistance of 3 multiplexers. Computation is provided by an arithmetic logic unit (ALU) capable of addition and NAND, operating on two general purpose 12-bit registers (“A” and “B”). A unique bit-flipper/rotator which allows subtraction and modulo-2 division (in addition to caching) is also implemented.

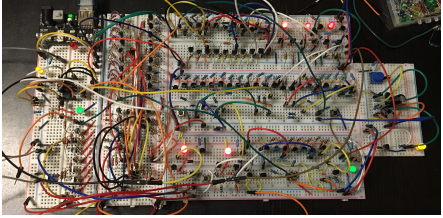
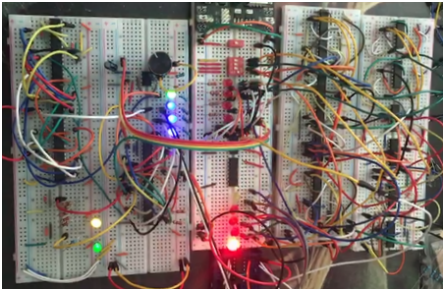
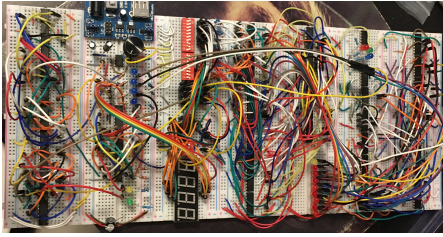
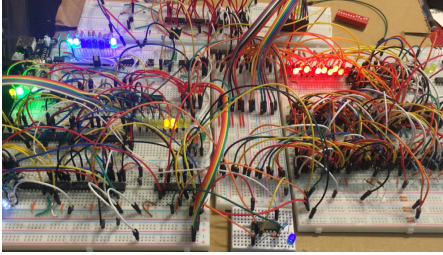
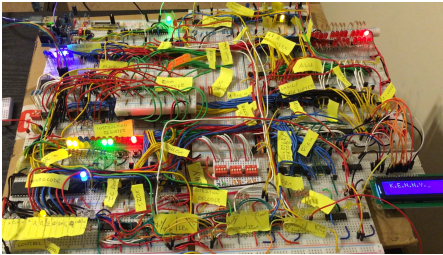
With no RAM in the classical sense, the memory map is significantly simplified, albeit at the expense of write time: programs may be written directly into the EEPROM with microcode installed on the machine in the exact way arithmetic values are stored. At present, error-free reads from EEPROM can be completed much faster than writes (~ 2 orders of magnitude). This is a key design restriction; future versions promise a true RAM to handle fast writes to memory, assuring prompt handling of intermediate values. On the upside, one benefit of this “slow” approach is non-volatility – all data is retained by the machine after shut-down.

As K.E.N.N.Y. has no stack paradigm, subroutines must be embedded into the program with specialized jump conditions. This is generally not a problem (as the machine remains Turing-complete), but it does pose certain challenges for purely calculative endeavors which benefit greatly from recursion. [For context, see Section 7, which outlines an obtuse implementation of the factorial function.] Nevertheless, a wide selection of machine code instructions allows many creative avenues of code design for the dedicated breadboard computer scientist.

The microcode comprising the kernel of K.E.N.N.Y.’s control unit is easily adjustable with nothing but tweezers and patience. This allows users to design application-specific instructions to suit their individual needs or desires. In the event of a particularly involved computation, it is relatively painless (though not straightforward) to implement a finite-state machine. Additionally, a 16x2 LCD display and two-button controller provides the hardware to run a few simple video games [see 8], assuming the coder refrains from writing to EEPROM (e.g., by using the flipper/rotator as a cache, or reading from the LCD). Development of these routines has proved both a challenging and rewarding experience for the author.

In essence, K.E.N.N.Y. is a flashing tangle of prototype board, wire, and ICs which costs less than a hamburger and three craft beers at your favorite hipster restaurant. He runs at least a million times slower than the computer used to typeset this document, and has less memory than an average microwave. And though he does not reheat burritos, he will happily replace his heart with a baked potato, if only you translate the ascii to his machine code.

2 Genealogy

K.E.N.N.Y. v1.0	2-bit parallel, finite-state No ICs		Add
K.E.N.N.Y. v2.0	4-bit serial, finite-state 555, NANDs, ANDs, Shift register		Add/subtract
K.E.N.N.Y. v3.0	8-bit serial, finite-state 555, NANDs, ANDs, ORs, XORs, Shift register		Add/subtract/Fibonacci/Collatz
K.E.N.N.Y. v4.0	12-bit parallel, finite-state 555s, NANDs, ANDs, ORs, XORs, Adders, Counters, Inverters		Add/subtract/Fibonacci/Collatz
K.E.N.N.Y. v5.0	12-bit parallel, Turing-complete 555s, NANDs, ANDs, ORs, XORs, EEPROMs, Adders, Counters, Inverters, Op Amps		Programmable

3 Block Diagram

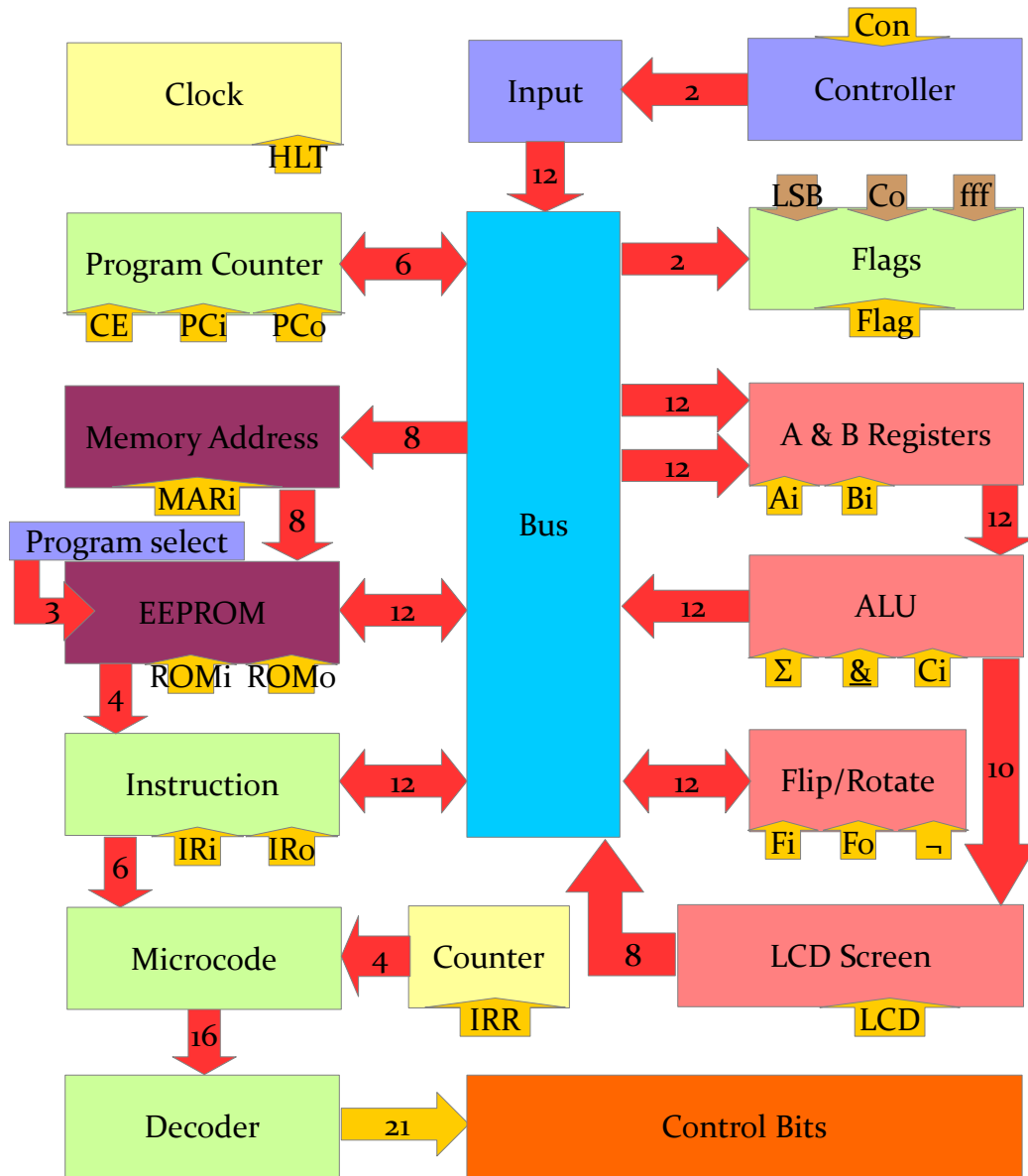


Figure 1: Schematic of K.E.N.N.Y. computer architecture. Connections in red are labeled by how many bits they transfer, and which direction these data are moved. Orange arrows represent respective control signals. The three brown arrows into the flags register show the conditions under which a program may branch.

4 Control Scheme

Fundamentally, a computer might be imagined as a “one-button” machine, where the instructions are set before each clock pulse. Upon receipt of a pulse, the machine executes the chosen instructions, increments some form of counter, and the process repeats *ad nauseum*. In K.E.N.N.Y.’s case, the control word is given by

$$\text{In } x \ x \ \text{Out } x \ x \ \text{Ai } \text{Bi } \Sigma \ \bar{\&} \ \text{Inv } \text{Ci } \text{Fi } \text{Clk } x \ x \ .$$

By multiplexing, we can manipulate more than 16 control bits. For clarity, we provide the following tables:

Selection	xx	Result	Selection	xx	Result
In = 1	00	PC in	Clk = 1	00	IR Reset
	01	ROM in		01	Count enable
	10	IR in		10	Halt
	11	MAR in		11	Latch flags
Out = 1	00	PC out	Clk = 0	01	LCD enable
	01	ROM out		10	Controller
	10	IR out			
	11	Flip out			

Control bit	Action on clock pulse	Microcode
PC in	Latch bus to program counter*	pci
IR in	Latch bus to instruction register	iri
ROM in	Latch bus to EEPROM data	romi
MAR in	Latch bus to EEPROM address	mari
Ai	Latch bus to register A	ai
Bi	Latch bus to register B	bi
Fi	Latch bus to flipper/rotator	fi
PC out	Send program counter value to bus	pco
IR out	Send instruction register value to bus	iro
ROM out	Send EEPROM value to bus	romo
Flip out	Send flipper/rotator value to bus	fo
Σ	Send adder value to bus	sum
$\bar{\&}$	Send NAND value to bus	nand
Inv	Invert bits in flipper/rotator	inv
Ci	Set adder’s carry input to 1	ci
IR Reset	Reset instruction register’s counter	irr
Count enable	Increment program counter	ce
Halt	Stop clock from running	halt
Latch flags	Latch flags register	flag
LCD enable	Send adder value to display	lcd
Controller	Enable input from controller	con

*Assuming the jump condition is satisfied.

5 Instruction Set

All machine code instructions to K.E.N.N.Y. are two bytes, and may be interpreted as

xxxx xx	xx	xxxx xxxx
Opcode	Xtra	Operand

The “xtra” bits are for encoding jump conditions, adding LCD functionality, enabling game controllers, and anything else a programmer can imagine! Thus, if we want K.E.N.N.Y. to add the contents of registers A and B, then store the result to memory address 0x80, we would use the instruction “0001 0000 1000 0000” or equivalently, “0x1080”. The following list elucidates which control signals are brought high by the microcode EEPROMs for each value of the counter. Unless otherwise noted, all instructions involve a fetch cycle on the first two clock ticks:

```
0000 pco mari          11110000 00000000
0001 romo iri ce       11010100 00000101
```

hence we will ignore these redundant cycles in the spirit of brevity.

5.1 0000 xx BOOT

Intializes the system. Clears registers, program counter, and memory address.

```
0000          00000000 00000000
.            .
.            .
.            .
1100 flag     00000000 00000111
1101 mari     11110000 00000000
1110 pci ai bi fi 10000011 00001000
1111 romo iri  11010100 00000000
```

5.2 0001 00 ADD

Adds registers A and B, saves result to operand’s memory address.
Latches flags register.

```
0010 iro mari  11111000 00000000
0011 sum romi flag 10100000 10000111
0100 irr       00000000 00000100
```

5.3 0010 00 AWC

Adds registers A and B, adds one, saves result to operand's memory address.
Latches flags register!

0010 iro mari	11111000 00000000
0011 sum romi ci flag	10100000 10010111
0100 irr	00000000 00000100

5.4 0011 00 NAN

NANDs registers A and B, saves result to operand's memory address.
Latches flags register!

0010 iro mari	11111000 00000000
0011 nand romi flag	10100000 01000111
0100 irr	00000000 00000100

5.5 0100 00 FLP

Flip bits of value at operand's memory address.
Latches flags register!

0010 iro mari	11111000 00000000
0011 romo fi	10100000 00001000
0100 fo inv fi	00011100 00101000
0101 fo romi flag	10111100 00000111
0110 irr	00000000 00000100

5.6 0101 00 ROT

Rotate bits of value at operand's memory address.
Latches flags register!

0010 iro mari	11111000 00000000
0011 romo fi	00010100 00001000
0100 fo romi flag	10111100 00100111
0101 irr	00000000 00000100

5.7 0110 00 INC

Increment value at operand's memory address.

0010 iro mari	11111000 00000000
0011 romo ai	00010110 00000000
0100 bi	00000001 00000000
0101 sum romi ci	10100000 10010000
0110 irr	00000000 00000100

5.8 0111 00 [xx] JMP

Loads program counter with operand's value if jump condition is satisfied.

00: unconditional

01: LSB odd

10: carry out

11: ALU = 0xffff

0010 iro pci	10011000	00000000
0011 irr	00000000	00000100

5.9 1000 00 LDA

Load value at operand's memory address into register A.

0010 iro mari	11111000	00000000
0011 romo ai	00010110	00000000
0100 irr	00000000	00000100

5.10 1001 00 LDB

Load value at operand's memory address into register B.

0010 iro mari	11111000	00000000
0011 romo bi	00010101	00000000
0100 irr	00000000	00000100

5.11 1010 00 MXX

Multiply value at operand's memory address by 2 (shift left).

Latches flags register!

0010 iro mari	11111000	00000000
0011 romo ai bi	00010111	00000000
0100 sum romi flag	10100000	10000111
0101 irr	00000000	00000100

5.12 1011 00 DXX

Divide value at operand's memory address by 2 (shift right).

Latches flags register!

0010 iro mari	11111000	00000000
0011 romo fi	00010100	00001000
0100 fo ai bi	00011111	00000000
0101 sum fi	00000000	10001000
0110 fi romi flag	10100000	00001111
0111 irr	00000000	00000100

5.13 1100 00 [xx] LCD

Perform operation on LCD display; data (if read) sent to B register.

00: instruction
01: read address
10: character
11: read data @ address

0010 iro ai	00011010	00000000
0011 bi	00000001	00000000
0100 lcd bi	00000001	00000001
0101 irr	00000000	00000100

5.14 1101 00 INP

Load bus value into operand's memory address. (Finicky!)

0010 iro mari	11111000	00000000
0011 romi halt	10100000	00000110
0100 halt	00000000	00000110
0101 irr	00000000	00000100

5.15 1110 00 WRI

User chooses memory location then writes data there. (How to program.)

0000 mari ai halt	11100010	00000110
0001 romi bi halt	10100001	00000110
0010 irr	00000000	00000100

5.16 1111 00 NOP

No operation; moves to next instruction.

0010 irr	00000000	00000100
----------	----------	----------

5.17 0001 01 SVP

Saves operand as a pointer at memory location 0xff.

0010 fi	00000000	00001000
0011 fo inv mari	11111100	00100000
0100 iro romi	10111000	00000000
0101 irr	00000000	00000100

5.18 0010 01 SWP

Swaps value at operand's memory location with pointer's value.

0010 ai bi fi	00000011	00001000
0011 fo inv mari	11111100	00100000
0100 romo mari	11110100	00000000
0101 romo fi	00010100	00001000
0110 iro mari	11111000	00000000
0111 romo ai	00010110	00000000
1000 fo fi	00011100	00001000
1001 fo romi	10111100	00000000
1010 fi	00000000	00001000
1011 fo inv mari	11111100	00100000
1100 romo mari	11110100	00000000
1101 sum romi	10100000	10000000
1110 irr	00000000	00000100

5.19 0011 01 FAN

ANDs value at operand's memory location with flip register.

0010 iro mari	11111000	00000000
0011 romo ai	00010110	00000000
0100 fo bi	00011101	00000000
0101 nand fi	00000000	01001000
0110 fo inv fi	00011100	00101000
0111 irr	00000000	00000100

5.20 0100 01 FAD

Adds value at operand's memory location to flip register.

Latches flags register!

0010 iro mari	11111000	00000000
0011 romo bi	00010101	00000000
0100 fo ai	00011110	00000000
0101 sum fi flag	00000000	10001111
0110 fo fi	00011100	00001000
0111 irr	00000000	00000100

5.21 0101 01 FSU

Subtracts value of operand's memory location from flip register.

Latches flags register!

0010 iro mari	11111000 00000000
0011 romo ai bi	00010111 00000000
0100 nand bi	00000001 01000000
0101 fo ai	00011110 00000000
0110 sum ci fi flag	00000000 10011111
0111 fo fi	00011100 00001000
1000 irr	00000000 00000100

5.22 0110 01 CWF

Compares flip register with value at operand's memory address.

n/a: op* < F
 car: op* > F
 fff: op* == F

0010 iro mari	11111000 00000000
0011 romo ai	00010110 00000000
0100 fo inv bi	00011101 00100000
0101 flag	00000000 00000111
0110 irr	00000000 00000100

5.23 0111 01 [xx] JIN

Jumps if controller button depressed. Use for games!

01: right button
 10: left button

0010 ai bi	00000011 00000000
0011 nand ai	00000010 01000000
0100 flag	00000000 00000111
0101 romo iri con	11010100 00000010
0110 iro pci	10011000 00000000
0111 irr	00000000 00000100

5.24 1000 01 LDF

Load value at operand's memory address into flip register.

0010 iro mari	11111000 00000000
0011 romo fi	00010100 00001000
0100 fo fi	00011100 00001000
0101 irr	00000000 00000100

5.25 1001 01 SAF

Saves value of flip register at operand's memory address.

0010 iro mari	11111000 00000000
0011 fo romi	10111100 00001000
0100 irr	00000000 00000100

5.26 1010 01 FMX

Multiplies flip register value by 2 (shift left).
Latches flags register!

0010 fo ai bi	00011111 00000000
0011 sum fi flag	00000000 10001111
0100 fo fi	00011100 00001000
0101 irr	00000000 00000100

5.27 1011 01 FDX

Divides flip register value by 2 (shift right).
Latches flags register!

0010 fo fi	00011100 00001000
0011 fo ai bi	00011111 00000000
0100 sum fi flag	00000000 10001111
0101 irr	00000000 00000100

5.28 1100 01 LCF

Performs LCD operation in flip register.

0010 fo ai	00011110 00000000
0011 bi	00000001 00000000
0100 lcd bi	00000001 00000001
0101 irr	00000000 00000100

5.29 1101 01 INF

Load bus value into flip register.

0010 fi halt	00000000 00001110
0011 halt	00000000 00000110
0100 fo fi	00011100 00001000
0101 irr	00000000 00000100

5.30 1111 01 CLR

Clears all registers.

0010 ai bi fi	00000011 00001000
0011 irr	00000000 00000100

5.31 0001 10 PXA

Adds value at operand's memory location to pointer's value (@0xffff).

0010 iro mari	11111000	00000000
0011 romo bi	00010101	00000000
0100 fi	00000000	00001000
0101 fo inv mari	11111100	00100000
0110 romo mari	11110100	00000000
0111 romo ai	00010110	00000000
1000 sum romi	10100000	10000000
1001 irr	00000000	00000100

5.32 0010 10 PXS

Subtracts value at operand's memory location from pointer's value.

0010 iro mari	11111000	00000000
0011 romo ai bi	00010111	00000000
0100 nand bi	00000001	01000000
0101 fi	00000000	00001000
0110 fo inv mari	11111100	00100000
0111 romo mari	11110100	00000000
1000 romo ai	00010110	00000000
1001 sum ci romi	10100000	10010000
1010 irr	00000000	00000100

5.33 0011 10 FOR

ORs value at operand's memory address with flip register.

0010 iro mari	11111000	00000000
0011 romo ai bi	00010111	00000000
0100 nand ai	00000010	01000000
0101 fo inv bi	00011101	00100000
0110 nand fi	00000000	01001000
0111 fo fi	00011100	00001000
1000 irr	00000000	00000100

5.34 0100 10 FIN

Increments value in flip register.

0010 fo ai	00011110	00000000
0011 bi	00000001	00000000
0100 sum ci fi	00000000	10011000
0101 fo fi	00011100	00001000
0110 irr	00000000	00000100

5.35 0101 10 FDE

Decrements value in flip register.

0010 ai bi	00000011	00000000
0011 nand bi	00000001	01000000
0100 fo ai	00011110	00000000
0101 sum fi	00000000	10001000
0110 fo fi	00011100	00001000
0111 irr	00000000	00000100

5.36 0110 10 CWB

Compares B register with value at operand's memory address.

0010 ai	00000010	00000000
0011 sum ai	00000010	10000000
0100 nand bi	00000001	01000000
0101 iro mari	11111000	00000000
0110 romo ai	00010110	00000000
0111 flag	00000000	00000111
1000 ai	00000010	00000000
1001 sum ai	00000010	10000000
1010 nand bi	00000001	01000000
1011 irr	00000000	00000100

5.37 0111 10 [01] JFO

Jumps if flip register LSB == 1.

0010 fo flag	00011100	00000111
0011 iro pci	10011000	00000000
0100 irr	00000000	00000100

5.38 1000 10 AFF

Adds A and F registers, places value in F register.

0010 fo bi	00011101	00000000
0011 sum fi	00000000	10001000
0100 fo fi	00011100	00001000
0101 irr	00000000	00000100

5.39 1001 10 BFF

Adds B and F registers, places value in F register.

0010 fo ai	00011110	00000000
0011 sum fi	00000000	10001000
0100 fo fi	00011100	00001000
0101 irr	00000000	00000100

5.40 1010 10 FMT

Multiplies flip register value by 3.
Latches flags register!

0010 fo ai bi	00011111	00000000
0011 sum ai	00000010	10000000
0100 fo bi	00011101	00000000
0101 sum fi flag	00000000	10001111
0110 fo fi	00011100	00001000
0111 irr	00000000	00000100

5.41 1011 10 FMV

Multiplies flip register value by 5.
Latches flags register!

0010 fo ai bi	00011111	00000000
0011 sum ai bi	00000011	10000000
0100 sum ai	00000010	10000000
0101 fo bi	00011101	00000000
0110 sum fi flag	00000000	10001111
0111 fo fi	00011100	00001000
1000 irr	00000000	00000100

5.42 1100 10 LFP

Uses flip register as pointer to address for LCD char/op.

0010 fo mari	11111100	00000000
0011 romo ai	00010110	00000000
0100 bi	00000001	00000000
0101 lcd bi	00000001	00000001
0110 irr	00000000	00000100

5.43 0001 11 PPA

Adds value at operand's memory location to pointer.

0010 iro mari	11111000	00000000
0011 romo bi	00010101	00000000
0100 fi	00000000	00001000
0101 fo inv mari	11111100	00100000
0110 romo ai	00010110	00000000
0111 sum romi	10100000	10000000
1000 irr	00000000	00000100

5.44 0010 11 PPS

Subtracts value of operand's memory location from pointer.

0010 iro mari	11111000	00000000
0011 romo ai bi	00010111	00000000
0100 nand bi	00000001	01000000
0101 fi	00000000	00001000
0110 fo inv mari	11111100	00100000
0111 romo ai	00010110	00000000
1000 sum ci romi	10100000	10010000
1001 irr	00000000	00000100

5.45 0011 11 FXO

XORs value at operand's memory address with flip register.

0010 iro mari	11111000	00000000
0011 romo ai	00010110	00000000
0100 fo bi	00011101	00000000
0101 nand bi	00000001	01000000
0110 fo ai	00011110	00000000
0111 nand fi	00000000	01001000
1000 romo ai	00010110	00000000
1001 nand ai	00000010	01000000
1010 fo fi	00011100	00001000
1011 fo bi	00011101	00000000
1100 nand fi	00000000	01001000
1101 fo fi	00011100	00001000
1110 irr	00000000	00000100

5.46 0100 11 AIF

Increments A register, adds to flip register.

Sets fff flag if A+1 == op*.

Use to sum like young Gauss! (for squaring...)

THIS NEEDS FIXED!

0010 bi	00000001	00000000
0011 sum ci ai	00000010	10010000
0100 fo bi	00011101	00000000
0101 sum fi	00000000	10001000
0110 fo fi	00011100	00001000
0111 sum ai bi	00000010	10000000
1000 nand ai	00000010	01000000
1001 romo bi	00010101	00000000
1010 bi flag	00000001	00000111
1011 sum bi	00000001	10000000
1100 nand ai	00000010	01000000
1101 irr	00000000	00000100

5.47 0101 11 NGF

Negates flip register (twos-complement).

0010 ai	00000010	00000000
0011 fo inv bi	00011101	00100000
0100 sum ci fi	00000000	10011000
0101 fo fi	00011100	00001000
0110 irr	00000000	00000100

5.48 0110 11 [11] JFM

Jumps PC to op if !(F&op*)+op* == fff.

Useful to check a single bit in flip register.

0010 iro mari	11111000	00000000
0011 romo ai	00010110	00000000
0100 fo bi	00011101	00000000
0101 nand bi	00000001	01000000
0110 romo ai	00010110	00000000
0111 flag	00000000	00000111
1000 iro pci	10011000	00000000
1001 irr	00000000	00000100

5.49 0111 11 [01] JFC

Jumps if flip register MSB == 1.

0010 fo fi	00011100	00001000
0011 fo flag	00011100	00000111
0100 fo fi	00011100	00001000
0101 iro pci	10011000	00000000
0110 irr	00000000	00000100

5.50 1000 11 SRI

Sets value at operand's memory location to PC + 1.
Necessary for subroutine calls.

0010 iro mari	11111000	00000000
0011 pco ai	00010010	00000000
0100 bi	00000001	00000000
0101 sum ci romi	10100000	10010000
0110 irr	00000000	00000100

5.51 1001 11 SRO

Loads value at operand's memory location to PC.
Necessary for subroutine calls.

0010 iro mari	11111000	00000000
0011 romo pci	10010100	00000000
0100 irr	00000000	00000100

5.52 1010 11 FSS

Adds flip to A register (saves in IR), multiplies flip by 2.
Can be used to multiply nibbles...

0010 fo bi	00011101	00000000
0011 sum romo iri	11010100	10000000
0100 fo ai bi	00011111	00000000
0101 sum fi	00000000	10001000
0110 fo fi	00011100	00001000
0111 fo inv ai	00011110	00100000
1000 bi	00000001	00000000
1001 romo ai bi flag	00010111	00000111
1010 nand bi	00000001	01000000
1011 iro ai	00011010	00000000
1100 nand ai bi	00000011	01000000
1101 nand ai	00000010	01000000
1110 irr	00000000	00000100

5.53 1011 11 FSX

Saves A register in IR, multiplies flip by 2.
Can be used to multiply nibbles...

0010 bi	00000001 00000000
0011 sum romo iri	11010100 10000000
0100 fo ai bi	00011111 00000000
0101 sum fi	00000000 10001000
0110 fo fi	00011100 00001000
0111 fo inv ai	00011110 00100000
1000 bi	00000001 00000000
1001 romo ai bi flag	00010111 00000111
1010 nand bi	00000001 01000000
1011 iro ai	00011010 00000000
1100 nand ai bi	00000011 01000000
1101 nand ai	00000010 01000000
1110 irr	00000000 00000100

5.54 1111 11 HLT

Halts operation.

0010 halt	00000000 00000110
-----------	-------------------

6 Function Table

high\low	00	01	10	11
0000	BOOT	BOOT	BOOT	BOOT
0001	ADD ^{*†}	SVP _f [†]	PXA _{abf} [†]	PPA _{abf} [†]
0010	AWC ^{*†}	SWP _{abf} [†]	PXS _{abf} [†]	PPS _{abf} [†]
0011	NAN ^{*†}	FAN _{ab}	FOR _{ab}	FXO _{ab}
0100	FLP _f ^{*†}	FAD _{ab} [*]	FIN _{ab} [‡]	AIF _b [*]
0101	ROT _f ^{*†}	FSU _{ab} [*]	FDE _{ab} [‡]	NGF [‡]
0110	INC _{ab} [†]	CWF _{ab} [*]	CWB _a [*]	JFM _{ab} [*]
0111	JMP	JIN _{ab} [*]	JFO [*]	JFC [*]
1000	LDA _a	LDF _f	AFF _b [‡]	SRI _{ab} [†]
1001	LDB _b	SAF [†]	BFF _a [‡]	SRO
1010	MXX _{abf} ^{*†}	FMX _{ab} ^{*‡}	FMT _{ab} ^{*‡}	FSS _b ^{*‡}
1011	DXX _{abf} ^{*†}	FDX _{ab} ^{*‡}	FMV _{ab} ^{*‡}	FSX _b ^{*‡}
1100	LCD _{ab}	LCF _{ab} [‡]	LFP _{ab} [‡]	LFM _{ab}
1101	INP [†]	INF _f [‡]		
1110	WRI ^{†°}	RDM [°]	WRL ^{†°}	RDL [°]
1111	NOP [‡]	CLR _{abf} [‡]		HLT [‡]

*Changes flags register

†Writes to EEPROM

‡Instruction has no operand

°No fetch cycle; use with caution!

_xDestroys information in register *x*

7 Example Code

With the exception of 7.5 and 7.7, the following examples use the flip register a cache. It may be an illuminating exercise to reconstruct their action using only the first column of the function table (warning: 7.6 cannot be done!). It is important to note that, by convention, each of these programs uses a **NOP** operation for line 0 (memory address 0x00). For clarity, we provide the corresponding machine code on the right-hand side of the page.

7.1 Increment

Standard debugging program. Should repeat after 4096 iterations. =^]

<pre> -3 increment.k -2 ===== -1 "Counts up, and up, and..." 0 ----- 1 //A/FIN/x00 % F->F+1 2 JMP[]/A % loop </pre>	<pre> 0x4800 0x7001 </pre>
--	------------------------------------

7.2 Fibonacci

A classic. Can be used to generate a repeatable sequence of pseudo-random numbers.

<pre> -3 fibonacci.k -2 ===== -1 "To a golden ratio..." 0 ----- 1 FIN/x00 % F->F+1 2 //A/AFF/x00 % A+F->F 3 BFF/x00 % B+F->F 4 JMP[]/A % loop </pre>	<pre> 0x4800 0x8800 0x9800 0x7002 </pre>
---	--

7.3 Bit shift

This looks interesting because division is accomplished by multiplying reversed numbers, leading to a “swooshing” effect.

<pre> -3 shift.k -2 ===== -1 "Fun register visual" 0 ----- 1 //B/FMX/x00 % F->F*2 2 FIN/x00 % F->F+1 3 JMP[car]/A % jump on carry 4 JMP[]/B % else loop 5 //A/FDX/x00 % F->F/2 6 JMP[car]/B % restart if done </pre>	<pre> 0xa400 0x4800 0x7205 0x7001 0xb400 0x7201 </pre>
---	--

7.4 Collatz conjecture

Probably the most beautiful thing K.E.N.N.Y. can do, and the reason I took the time to build him. For the unfamiliar, given some $n_0 \in \mathbb{N}$,

$$n_{k+1} = \begin{cases} n_k/2, & n_k \text{ even} \\ 3n_k + 1, & n_k \text{ odd} \end{cases}$$

The conjecture is that all n_0 will eventually fall into the $1 \rightarrow 4 \rightarrow 2$ cycle. As this is a modulo-2¹² enumeration, roughly 1/3 of all numbers will never halt.

<pre> -3 collatz.k -2 ===== -1 "Please prove this!" 0 ----- 1 //C/INF/x00 % input to flip 2 //B/JF0[01]/A % jump if odd 3 FDX/x00 % F->value/2 if even 4 JMP[]/B 5 //A/CWF/x81(=x001) % check if value=1 6 JMP[fff]/C % restart if so 7 FMX/x00 % F->2*value 8 AFF/x00 % F->3*value 9 FIN/x00 % F->3*value+1 10 JMP[]/B </pre>	<pre> 0xd400 0x7a05 0xb400 0x7002 0x6481 0x7301 0xa400 0x8800 0x4800 0x7002 </pre>
---	--

7.5 Display name

Essentially a standard “Hello world!” routine. Nice for debugging LCDs, and display.

<pre> -3 kenny.k -2 ===== -1 "I can spell!" 0 ----- 1 LCD/?x038 % initializes lcd 2 LCD/?x00f % turn on cursor 3 //A/LCD/?x082 % puts cursor to (0,3) 4 LCD/"x4b" % K 5 LCD/"x2e" % . 6 LCD/"x45" % E 7 LCD/"x2e" % . 8 LCD/"x4e" % N 9 LCD/"x2e" % . 10 LCD/"x4e" % N 11 LCD/"x2e" % . 12 LCD/"x59" % Y 13 LCD/"x2e" % . 14 LCD/?x001 % clear screen 15 JMP[]/A % loop </pre>	<pre> 0xc038 0xc00f 0xc082 0xc24b 0xc22e 0xc245 0xc22e 0xc24e 0xc22e 0xc24e 0xc22e 0xc259 0xc22e 0xc001 0x7003 </pre>
--	---

7.6 Shooter

This was an incredibly fun time to write. Besides pushing the current version of K.E.N.N.Y. to his limits, it is just a generally good time (despite the lack of enemies, levels, score, or objective). Running 7.5 or something similar before playing allows you the joy of clearing the screen with your missile...

```

-9 shooter.k
-8 =====
-7 "Super basic shooter game"
-6 -----
-5 ?x010 -> Z + x80 % jump for shot value=16
-4 ?x080 -> H + x80 % jump for shot on
-3 ?msb = x40(=800) % msb toggle
-2 ?top = x41(=082) % top shot
-1 ?bot = x42(=8c2) % bottom shot
0 ?onof = x44(=080) % shot on/off
1 LCD/?x038 % initializes lcd
2 LCD/?x00c % turn off cursor
3 LCD/?x081 % puts cursor to (0,2)
4 LCD/"x3e" % draws ship
5 //D/JIN[01]/A % check up/down
6 //G/JIN[10]/B % check fire
7 JFM[fff]/H + 0x80 % check shot on
8 JMP[]/D % do nothing
9 //H/LCF/x00 % place cursor
10 LCD/"x20" % draw blank
11 FIN/x00 % increment flip
12 JFM[fff]/Z + 0x80 % exit if shot off screen
13 LCD/"xa5" % draw exhaust
14 LCD/"x7e" % draw missile
15 JMP[]/D
16 //Z/FX0/?onof % turn shot off *forgot:17 jmp[]/D*
17 //A/FAD/?msb % toggle up/down
18 JMP[car]/E
19 LCD/?x081 % up
20 LCD/"x20" % draw blank
21 LCD/?x0c1 % down
22 JMP[]/F
23 //E/LCD/?x0c1 % down
24 LCD/"x20" % draw blank
25 LCD/?x081 % up
26 //F/LCD/"x3e" % draw ship
27 JMP[]/G
28 //B/JFM[fff]/H + 0x80 % check shot on
29 JFC[01]/J % check up/down
30 LDF/?top % if up, set pos.
31 JMP[]/H
32 //J/LDF/?bot % same if down
33 JMP[]/H

```

7.7 Factorial

Naïve implementation which demonstrates most of the standard (1st column) functions.

```

-13 factorial.k
-12 =====
-11 "Computes n*(n-1)*...*2*1"
-10 -----
-9 ?null = x40 (=000)
-8 ?fff = x4f (=fff)
-7 ?nopp = x44
-6 ?n = x80 (=value)
-5 ?q = x81
-4 ?k = x8f
-3 ?a = x88
-2 ?b = x8c
-1 ?c = x8e
0 AWC/?c % c->1 0x208e
1 ADD/?k % k->0 0x108f
2 LDA/?n % regA = n 0x8080
3 ADD/?q % q->n 0x1081
4 FLP/?q % q->!q (!n) 0x4081
5 //C/LDA/?k % regA = k 0x808f
6 LDB/?q % regB = q 0x9081
7 ADD/?nopp % set flag 0x1044
8 JMP[fff]/A % jump if k=n 0x7321
9 INC/?k % k->k+1 0x608f
10 LDA/?null % regA = 0 0x8040
11 LDB/?k % regB = k 0x908f
12 ADD/?a % a->k 0x1088
13 LDB/?c % regB = c 0x908e
14 ADD/?b % b->c 0x108c
15 LDB/?null % regB = 0 0x9040
16 ADD/?c % c->0 0x108e
17 LDB/?b % regB = b 0x908c
18 ADD/?b % b = b (need to set flag) 0x108c
19 //D/JMP[odd]/B % jump if b odd 0x721e
20 LDA/?fff % regA = fff 0x804f
21 LDB/?b % regB = b 0x908c
22 ADD/?NOP % set flag 0x108e
23 JMP[fff]/C % jump if b=0 0x7306
24 //E/MXX/?a % a->2*a 0xa088
25 DXX/?b % b->b/2 0xb08c
26 LDA/?c % regA = c 0x808e
27 JMP[]/D % jump 0x7014
28 //B/LDA/?c % regA = c 0x808e
29 LDB/?a % regB = a 0x9088
30 ADD/?c % c->a+c 0x108e
31 JMP[]/E 0x7019
32 //A/LDB/?null % clear regB 0x9040
33 //F/LDA/?c % show answer 0x808e
34 JMP[]/F % loop forever 0x7022

```

8 Game Development

By allowing *reads* from the LCD's internal RAM, we can easily implement collision detection, or other more advanced behavior. This section briefly outlines some rough ideas for entertaining/interactive programs. Most involve using the flip register as a pointer to memory locations beyond 0x3f, which allows custom characters, lengthy setup, &c. to occur without distressing the program's run-time memory.

8.1 Frog vs. Flies



After the proof of principle that is [7.6](#), we now use side scroll, enemies, and collision detection.

```
1 ?cus1 = x40(x213)
2       = x41(x215)
3       = x42(x20c)
4       = x43(x21f)
5       = x44(x20c)
6       = x45(x215)
7       = x46(x213)
8       = x47(x200)
9 ?cus2 = x48(x201)
10      = x49(x202)
11      = x4a(x20c)
12      = x4b(x21e)
13      = x4c(x20c)
14      = x4d(x202)
15      = x4e(x201)
16      = x4f(x200)
17 ?loc1 = x50(x08c) % enemy location 1 -- 12up
18 ?guy1 = x51(x201) % enemy 1
19 ?loc2 = x52(x0cf) % enemy location 2 -- 15down
20 ?guy2 = x53(x201) % enemy 2
21 ?loc3 = x54(x092) % enemy location 3 -- 18up
22 ?guy3 = x55(x201) % enemy 3
23 ?loc4 = x56(x0d3) % enemy location 4 -- 19down
24 ?guy4 = x57(x201) % enemy 4
25 ?loc5 = x58(x094) % enemy location 5 -- 20up
26 ?guy5 = x59(x201) % enemy 5
27 ?loc6 = x5a(x0dd) % enemy location 6 -- 29down
28 ?guy6 = x5b(x201) % enemy 6
```

```

29 ?loc7 = x5c(x09f) % enemy location 7 -- 31up
30 ?guy7 = x5d(x201) % enemy 7
31 ?loc8 = x5e(x0a5) % enemy location 8 -- 37up
32 ?guy8 = x5f(x201) % enemy 8
33 ?loc6 = x60(x0e5) % enemy location 9 -- 37down
34 ?guy6 = x61(x201) % enemy 9

1 LCD/?x038 % initialize
2 LCD/?x00c % cursor off
3 LCD/?x001 % clear
4 NOP/x00 % END INITIALIZATION
5 LCD/?x040 % start custom chars
6 LDF/x80(x040) % load pointer
7 //DRAWS/LCP/x00 % perform lcd command @ pointer value
8     FIN/x00 % increment flip
9     CWF/x81(x062) % compare with limit
10    JMP[fff]/START % jump if done
11    JMP[]/DRAWS
12 //START/LCD/?x081 % goto start
13    LCD/"200" % draw ship
14    LDF/x70(x081) % set initial position
15    NOP/x00 % END DRAW SCREEN
16 //LOOPA/JIN[01]/UPDOWN % check up/down
17 //LOOPB/JIN[10]/SHOOT % check shot
18    JMP[]/SHIFT % shift screen
19    //UPDOWN/LCF/x00 % goto ship pos
20        LCD/"x220" % draw blank
21        FX0/x0(x040) % xor position
22        LCF/x00 % goto new pos
23        LCD/"x200" % draw ship
24        JMP[]/LOOPB
25        NOP/x00 % END UP/DOWN
26    //SHOOT/LCF/x00 % goto pos
27        LCD/?x014 % move right
28        LCD/"x23d" % draw laser
29        LCD/"x23d" % draw laser
30        LCD/"x22a" % draw tip
31        LCD/?x010 % move left
32        LCD/?x004 % change input to left
33        LCD/"x220" % draw blank
34        LCD/"x220" % draw blank
35        LCD/"x220" % draw blank
36        LCD/?x006 % change input to right
37        JMP[]/SHIFT
38        NOP/x00 % END SHOOT
39    //SHIFT/LCF/x00 % goto ship pos
40        LCD/"x220" % draw blank
41        FIN/x00 % increment pos
42        LCF/x00 % must set ram address for read apparently
43        LCD/?x300 % send char data to regB
44        CWB/x01(x001) % set fff flag if space has enemy
45        JMP[fff]/LOSER % jump to end game

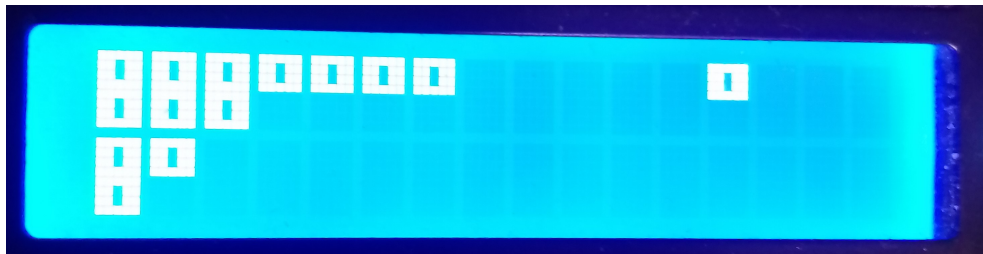
```

```

46         LCD/?x010 % mem check moves cursor, must reverse!
47         LCD/"x200" % draw ship
48         LCD/?x018 % shift left
49         JMP[]/LOOPA
50         NOP/x00 % END SHIFT
51 //LOSER/LCD/?x001
52         LCD/?x083 %
53         LCD/"x247" % G
54         LCD/"x261" % a
55         LCD/"x26d" % m
56         LCD/"x265" % e
57         LCD/"x220" %
58         LCD/"x24f" % O
59         LCD/"x276" % v
60         LCD/"x265" % e
61         LCD/"x272" % r
62         LCD/"x221" % !
63         HLT/x00

```

8.2 Stack-a-Block



An incredibly basic game in the spirit of Tetris, albeit lacking rotation and line-clearing. A game over is possible, however.

```

1 ?gogo = xbb(x038) % no space to intialize in main program!
2       = xbc(x00c) % so do it here!
3       = xbd(x001)
4       = xbe(x006)
5       = xbf(x040)
6 ?cus0 = xc0(x21f) % "top" block
7       = xc1(x21b)
8       = xc2(x21b)
9       = xc3(x21f)
10      = xc4(x200)
11      = xc5(x200)
12      = xc6(x200)
13      = xc7(x200)
14 ?cus1 = xc8(x200) % "bottom" block
15      = xc9(x200)
16      = xca(x200)
17      = xcb(x200)
18      = xcc(x21f)

```

```

19      = xcd(x21b)
20      = xce(x21b)
21      = xcf(x21f)
22      ?cus2 = xd0(x21f) % "full" block
23      = xd1(x21b)
24      = xd2(x21b)
25      = xd3(x21f)
26      = xd4(x21f)
27      = xd5(x21b)
28      = xd6(x21b)
29      = xd7(x21f)
30      ?start = xd8(x080) % draw blocks @ left end of screen
31      = xd9(x202)
32      = xda(x0c0)
33      = xdb(x202)

1  LDF/x80(x0bb) % load pointer
2  //BLOCK/LCP/x00 % do stuff!
3      FIN/x00 % increment
4      CWF/x81(x0dc) % check limit
5      JMP[fff]/NEWW % exit if done
6      JMP[]/BLOCK % else loop
7  //NEWW/LDF/x82(x08f) % load start pos
8      LCF/x00 % goto pos
9      LCD/"x200" % draw up
10     NOP/x00 % END INITIALIZATION
11  //CHANG/JIN[01]/LEFFT
12     JIN[10]/RIGHT
13     JMP[]/LOOOP
14  //LEFFT/JFC[odd]/DERPA % if down, switch top/bottom
15     JMP[]/MYGOD % else don't worry
16     //RIGHT/JFC[odd]/MYGOD % if up, don't worry
17     //DERPA/LCF/x00 %
18         LCD/"x220" % draw blank
19         FX0/x70(x040) % xor shit -> switch t/b
20     //MYGOD/jad/x71(x800) % switch up/down
21  //LOOOP/FDE/x00 % decrement flip
22     LCF/x00 % goto left of pos
23     LCD/?x300 % read data
24     CWB/x61(x002) % see if full
25     JMP[fff]/STOOP
26     CWB/x62(x001) % see if down
27     JMP[fff]/CHEKD %
28     CWB/x63(x000) % see if up
29     JMP[fff]/CHEKU
30     LCF/x00 % go back to left of pos
31     JFC[odd]/PRNTD % must be blank! check current block
32     LCD/"x200" % if up, print that
33     JMP[]/REDRW
34     //PRNTD/LCD/"x201" % print down
35         JMP[]/REDRW
36         NOP/x00

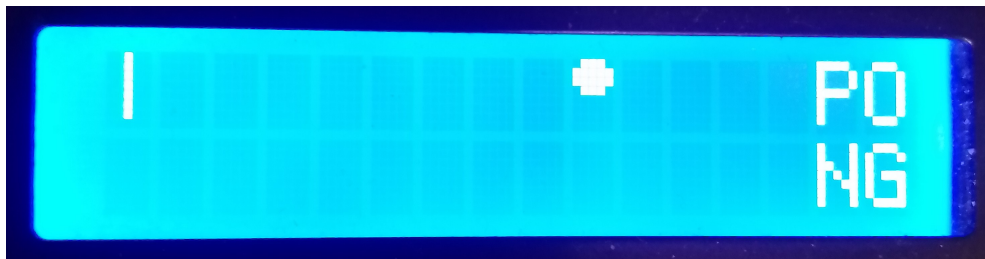
```

```

37 //CHEKU/JFC[odd]/PRNTF % up on down -> whole
38     JMP[]/STOOP % up on up, do nothing
39 //CHEKD/JFC[odd]/STOOP % down on down, do nothing
40 //PRNTF/LCF/x00 % go back to left of pos
41     LCD/"x202" % draw whole block
42 //REDRW/FIN/x00 % increment to get to pos
43     LCF/x00 % goto pos
44     LCD/?x300 % read data
45     CWB/x61(x002) % see if full
46     LCF/x00 % go back to pos
47     JMP[fff]/RUDWN % if full, check if block is up
48     LCD/"x220" % else can print space
49     JMP[]/MOVIN
50 //RUDWN/JFC[odd]/OHYEA % jump if current is down
51     LCD/"x201" % draw down
52     JMP[]/MOVIN
53 //OHYEA/LCD/"x200" % current is down, draw up
54     NOP/x00
55 //MOVIN/FDE/x00 % set new position
56     LCF/x00 % go to pointer
57     JMP[]/CHANG
58 //STOOP/JFM[fff]/{x80+LOSER}(x00e) % check for game over
59     JMP[]/NEWWW % else do new block
60 //LOSER/LCD/?x001
61     LCD/?x087
62     LCD/"x221"
63     HLT/x00

```

8.3 K.E.N.N.Y. Pong



An attempt at cloning the classic Atari hit, but essentially a one-sided, massive failure. Fun though!

```

1 ?gogo = xbb(x038) % intialization
2       = xbc(x00c)
3       = xbd(x001)
4       = xbe(x006)
5       = xbf(x040)
6 ?cus0 = xc0(x20e) % "top" ball
7       = xc1(x21f)
8       = xc2(x21f)
9       = xc3(x20e)

```

```

10      = xc4(x200)
11      = xc5(x200)
12      = xc6(x200)
13      = xc7(x200)
14      ?cus1 = xc8(x200) % "bottom" ball
15      = xc9(x200)
16      = xca(x200)
17      = xcb(x200)
18      = xcc(x20e)
19      = xcd(x21f)
20      = xce(x21f)
21      = xcf(x20e)
22      ?start = xd0(x080) % draw paddle
23      = xd1(x27c)
24      = xd2(x0c0)
25      = xd3(x220)
26      = xd4(x08e)
27      = xd5(x250) % P
28      = xd6(x24f) % O
29      = xd7(x0ce)
30      = xd8(x24e) % N
31      = xd9(x247) % G

1 LDF/x80(x0bb) % load pointer
2 //BLOCK/LCP/x00 % do stuff!
3     FIN/x00 % increment
4     CWF/x81(x0da) % check limit
5     JMP[fff]/NEWW % exit if done
6     JMP[]/BLOCK % else loop
7 //NEWW/LDF/x82(x088) % load starting ball
8     NOP/x00 % END INITIALIZATION
9 //BALLL/LCF/x00 % goto pos
10    LCD/"x220" % clear ball
11    LCD/?x300 % get data -- holy shit this works!
12    CWB/xa0(x000) % see if top
13    JMP[fff]/CEILY % jump if top
14    JFM[fff]/{x40 + HITTT}(x040) % must be bottom... so check floor
15    //NOHIT/FX0/xa1(x080) % no collision? xor to set bot->top
16    //WHCHW/JFM[fff]/{x40 + MOVED}(x400) % jump if move down
17    JFM[fff]/{x40 + FLIPP}(x040) % must be moving up... jump if down
18    JMP[]/MOVIN
19    //CEILY/JFM[fff]/{x40 + WHCHW}(x040) % check if down
20    FX0/xa1(x080) % xor top/bot
21    //HITTT/FX0/xa1(x080) % xor top/bot
22    FX0/xa2(x400) % xor move up/down
23    //MOVIN/JFC[odd]/RIGHT % jump if move right
24    //LEFFT/FAD/xa3(x00e) % add 14 to flip
25    JFM[fff]/{x40 + LCHEK}(x00f) % check flip = 1
26    FSU/xa4(x00f) % guess not! so subtract 15...
27    //PRINT/JFM[fff]/{x40 + PRNTB}(x080) % see if bot
28    FOR/xa1(x080) % if not, must or w/ x080
29    LCF/x00 % goto pos

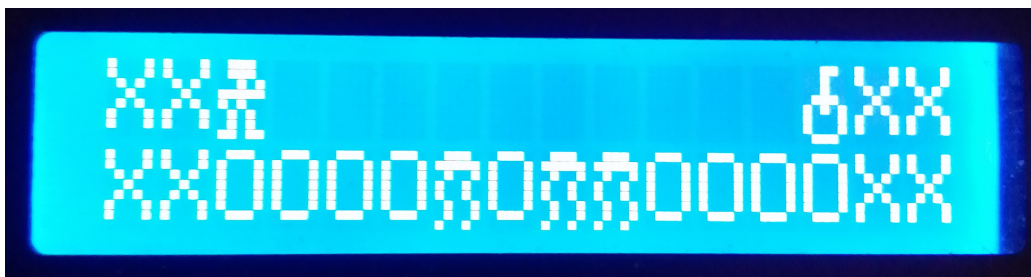
```

```

30         LCD/"x200" % print top
31         JMP[]/INPUT % jump out
32 //PRNTB/LCF/x00 % goto pos
33         LCD/"x201" % print bot
34         NOP/x00
35 //INPUT/JIN[01]/LPADD % check left button
36         JIN[10]/RPADD % check right button
37         JMP[]/BALLL
38 //LPADD/LCD/?x080 % goto left pos
39         LCD/"x27c" % print paddle
40         LCD/?x0c0 %
41         LCD/"220" % print blank
42         JMP[]/BALLL
43 //RPADD/LCD/?x080
44         LCD/"x220" % print blank
45         LCD/?x0c0 % goto right pos
46         LCD/"27c" % print paddle
47         JMP[]/BALLL
48         NOP/x00
49 //MOVED/JFM[fff]/{x40 + MOVIN}(x040) % jump to move if down
50 //FLIPP/FX0/xa6(x040) % xor up/down
51         JMP[]/MOVIN
52 //RIGHT/JFM[fff]/{x40 + SLAPP}(x00d) % check flip = 13
53         FIN/x00 % no? okay to increment!
54         JMP[]/PRINT % else print
55 //LCHEK/FDE/xa7(x00f) % subtract 15
56         FOR/xa1(x080) % or w/ x080
57         LCF/x00 % goto pos
58         LCD/?x300 % get data
59         CWB/xa5(x020) % see if empty
60         JMP[fff]/NEWW % if so, oops! new ball
61         FIN/x00 % have to increment now!
62 //SLAPP/FAD/xa8(x800) % change move l/r
63         JMP[]/PRINT % now print what was there!

```

8.4 Jellyfish Bridge



An homage to the well-received “Purple Turtles” for the Commodore 64. Pretty sweet, but hard as shit!

```
1| ?gogo = x90(x038)
```

```

2      = x91(x00c) % use x00f initially!
3      = x92(x001) % clear screen
4      = x93(x006) % cursor moves right
5      = x94(x083) % goto 0,3
6      = x95(x24c) % L
7      = x96(x26f) % o
8      = x97(x261) % a
9      = x98(x264) % d
10     = x99(x269) % i
11     = x9a(x26e) % n
12     = x9b(x267) % g
13     = x9c(x22e) % .
14     = x9d(x22e) % .
15     = x9e(x22e) % .
16     = x9f(x040) % start custom chars
17 ?cus0 = xa0(x20e) % walking dude
18       = xa1(x20e)
19       = xa2(x205)
20       = xa3(x21f)
21       = xa4(x214)
22       = xa5(x20a)
23       = xa6(x20a)
24       = xa7(x21b)
25 ?cus1 = xa8(x20e) % turtle up
26       = xa9(x21f)
27       = xaa(x209)
28       = xab(x212)
29       = xac(x212)
30       = xad(x209)
31       = xae(x209)
32       = xaf(x212)
33 ?cus2 = xb0(x200) % turtle down
34       = xb1(x200)
35       = xb2(x20e)
36       = xb3(x21f)
37       = xb4(x209)
38       = xb5(x212)
39       = xb6(x209)
40       = xb7(x212)
41 ?cus3 = xb8(x206) % cherry
42       = xb9(x204)
43       = xba(x204)
44       = xbb(x20e)
45       = xbc(x215)
46       = xbd(x211)
47       = xbe(x211)
48       = xbf(x20e)
49 ?start = xc0(x080) % goto 0,0
50         = xc1(x258) % X
51         = xc2(x258) % X
52         = xc3(x200) % dude
53         = xc4(x220)

```

```

54      = xc5(x220)
55      = xc6(x220)
56      = xc7(x220)
57      = xc8(x220)
58      = xc9(x220)
59      = xca(x220)
60      = xcb(x220)
61      = xcc(x220)
62      = xcd(x220)
63      = xce(x203) % cherry
64      = xcf(x258) % X
65      = xd0(x258) % X
66      = xd1(x0c0) % goto 1,0
67      = xd2(x258) % X
68      = xd3(x258) % X
69      = xd4(x24f) % 0
70      = xd5(x24f) % 0
71      = xd6(x24f) % 0
72      = xd7(x24f) % 0
73      = xd8(x201) % turtle 1
74      = xd9(x24f) % 0
75      = xda(x201) % turtle 2
76      = xdb(x201) % turtle 3
77      = xdc(x24f) % 0
78      = xdd(x24f) % 0
79      = xde(x24f) % 0
80      = xdf(x24f) % 0
81      = xf0(x258) % X
82      = xf1(x258) % X

1 //NEWW/LDF/x80(x090) % load pointer
2 //MAPPP/LCP/x00 % do stuff!
3     FIN/x00 % increment
4     CWF/x81(x0f2) % check limit
5     JMP[fff]/START % exit if done
6     JMP[]/MAPPP % else loop
7 //START/LDF/x82(x082) % load initial pos
8 //LOOOP/LCD/?x014 % move cursor right
9     JIN[01]/LMOVE
10    JIN[10]/RMOVE
11    JMP[]/LOOOP
12 //LMOVE/JFC[odd]/GOLEF
13    JMP[]/TURTS
14    //GOLEF/FX0/x83(x800)
15        JMP[]/TURTS
16 //RMOVE/FOR/x83(x800)
17 //TURTS/LCD/?x100
18    CWB/x84(x04a)
19    JMP[car]/TURT1 % jump if x4a > address
20    CWB/x85(x055)
21    JMP[car]/TURT2 % jump if x55 > address
22    CWB/x86(x060)

```

```

23     JMP[car]/TURT3 % jump if x60 > address
24     JMP[]/CHECK
25     //TURT1/LCD/?0c4
26         JMP[]/SWITC
27     //TURT2/LCD/?0c6
28         JMP[]/SWITC
29     //TURT3/LCD/?0c7
30     //SWITC/LCD/?300 % get current turtle
31         CWB/x87(x002) % see if down
32         LCD/?x010 % must move left!
33         JMP[fff]/TDOWN
34         LCD/"202" % up? print down
35         JMP[]/CHECK
36         //TDOWN/LCD/"201" % move turtle up
37     //CHECK/LCF/x00 % goto pos
38         LCD/"220" % draw blank
39         JFC[odd]/RIGHT % jump if moving right
40         CWF/x88(x082) % see if left wall
41         JMP[fff]/WALKK
42         FDE/x00 % decrement
43         CWF/x89(x482) % see if moving to score
44         JMP[fff]/SCORE
45         JMP[]/WALKK
46     //RIGHT/CWF/x8a(x88d) % see if right wall is next
47         JMP[fff]/WALKK
48         FIN/x00 % increment
49         CWF/x8b(x88d) % see if moving to cherry
50         JMP[fff]/CHERY
51     //WALKK/LCF/x00
52         LCD/"200" % draw dude
53         FX0/x8c(x040) % xor to go below
54         LCF/x00 % goto pos
55         LCD/?x300 % get data
56         CWB/x8d(x002) % see if down turtle
57         JMP[fff]/NEWW
58         FX0/x8c(x040) % xor to come back
59         JMP[]/L000P
60     //SCORE/LCD/?x08d
61         LCD/"x203" % draw cherry!
62     //CHERY/FX0/x8e(x400) % toggle cherry in inventory
63         JMP[]/WALKK % keep walking

```

9 Next Steps

Although K.E.N.N.Y. has come an incredible distance in five iterations, he undoubtedly has further to go. We briefly summarize the pros/cons of the current machine, and discuss what will provide v6.0 the proverbial leg-up.

What to keep

- No other hardware – EEPROMS programmable by hand, no cross-assemblers necessary.
- Reliability – non-volatile memory and low error rate when properly powered.
- Simplicity – a powerful tool for sanity and education.
- Philosophy – make a simple computer that can be enjoyed and understood.

What to remove

- Substitution of ICs – buffers were made with ANDs and diodes, (de-)multiplexers with ANDs and ORs; substantially affects space requirements.
- “Daisy chain” power supply topology – ground loops and voltage inadequacies are almost impossible to avoid.

What to add

- True RAM – obviously! Ability to read LCD is nice, but wildly inefficient.
- Stack pointers and general purpose registers – enable less “clunky” recursion, and more efficient algorithms in general.
- Move to printed circuit board (PCB) for modularity, ease of construction, and erasure of power supply problems.
- More I/O – a keyboard buffer, output register, and interrupts would open many avenues (ease of use, game development, etc.).
- Operating system – despite the challenge, it would be wonderful to create a more universal venue for software. The dream would be the ability to write assembly code.

Thanks for your time!

